(NASA-CR-160487) RESULTS OF TESTS USING A 0.03-SCALE MODEL (47-OTS) OF THE SPACE SHUTTLE INTEGRATED VEHICLE IN THE NASA/AMES RESEARCH CENTER 9 X 7 FOOT SUPERSONIC WIND TUNNEL (IA184), VOLUME 2 (Chrysler Corp.)

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DMS-DR-2456 NASA-CR-160,487 VOLUME 2 OF 2

RESULTS OF TESTS USING A 0.03-SCALE MODEL (47-OTS) OF
THE SPACE SHUTTLE INTEGRATED VEHICLE IN THE NASA/AMES
RESEARCH CENTER 9 X 7 FOOT SUPERSONIC WIND TUNNEL

(IA184)

bу

J. J. Daileda

Rockwell International Space Systems Group

Prepared under NASA Contract Number NAS9-13247

bу

Data Management Services
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for

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Johnson Space Center
National Aeronautics and Space Administration
Houston, Texas

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WIND TURNEL SPECIFICS:

Test Number:

ARC97SWTA347

MASA Series Number:

IA184

Model Wumber:

47-0TS

Test Dates:

April 6, 1979 through April 13, 1979

Occupancy Hours:

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DMS-DR-2456 NASA-CR-160,486 VOLUME 1 OF 2

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ABSTRACT

An experimental investigation (IA184) was conducted in the MASA/Ames Research Center Unitary Plan Wind Tunnel 9 x 7 foot supersonic leg from April 6 through 13, 1979. This test was a continuation of test IA105B which ran from January 24, 1978 until terminated on February 2, 1978 due to a problem with the UPWT main drive system.

The objectives of the test were to obtain: distributed pressure data on each vehicle element and component as affected by elevon deflection; wing load indicator data; orbiter force and moment data; elevon hinge moments; and four component vertical tail force data. A secondary objective of the test was to obtain pressure data on a simulated ascent air data system probe mounted in the nose of the external tank.

Data were obtained at Mach numbers of 1.55, 1.8, 2.2 and 2.5 at a Reynolds number per foot of 3.5 x 10⁶. Data were obtained by making angle-of-attack sweeps at a series of constant angles-of-sideslip. The range of angles-of-attack and sideslip was between 16 degrees.

ABSTRACT (Concluded)

Configuration variations consisted of a series of differential inboard/outboard elevon angle settings at zero aileron angle, with and without the Shuttle Infrared Leeside Temperature Sensing (SILTS) pod on the orbiter.

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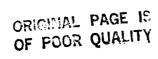
VOLUME 2 (Pressure Data - Microfiche)

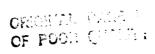
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INTRODUCTION

The 0.03-scale model (47-0TS) of the space shuttle integrated vehicle was tested in the MASA/Ames Unitary Plan Wind Tunnel 9 x 7-foot supersonic leg between April 6 and 13, 1979. This test, designated IA184, used a total of 33 test hours in the facility. Test IA184 was a continuation of test IA105B which ran in the same facility from January 24, 1978 until it was terminated on February 2, 1978 due to a problem with the UPWT main drive system.

Data were obtained at Mach numbers of 1.55, 1.8, 2.2 and 2.5 at a Reynolds number per foot of 3.5 \times 10⁶. Angle-of-attack sweeps were run at constant angles-of-sideslip over a range of angles-of-attack and sideslip between \pm 6 degrees.

Configuration variations consisted of a series of differential inboard/outboard elevon angle setting at zero aileron angle, with and without the Shuttle Infrared Leeside Temperature Sensing (SILTS) pod on the orbiter.

The model was instrumented with a total of 762 pressure taps distributed as follows: 443 on the orbiter, 181 on the external tank, and 138 on the solid rocket booster. Orbiter forces and moments were measured by a six-component strain gauge balance. Wing torsion, bending and shear were measured using a three-component balance (gauged wing-mounting beam) on the right side of the model. The right elevons were each mounted on a strain-gauged beam to measure hinge moments. Both "pressure" and "force" vertical tails were used during the test. The

INTRODUCTION (Continued)

"force" vertical had a dummy balance gauged to measure shear, bending, torsion and the pitching moment of the vertical tail.

This report provides a description of the test consisting of remarks on the conduct of the test, descriptions of the model and the test facility, details on test procedure, information on data reduction, and both plotted and tabulated test results.

This report consists of 1 volume of plotted pressure data and tabulated force data; and 1 volume of tabulated pressure data on microfiche.

The volumes are arranged in the following manner:

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HOMENCLATURE

SYMBOL		DEFINITION
A		Area over which P _i acts, ft ² .
B _{vt}	-	Vertical tail bending moment, in-lbs.
$\mathbf{B}_{\mathbf{W}}$	-	Wing bending moment, in-lbs.
c_{A_b}	CAB	Orbiter base axial force coefficient.
$c_{\mathbf{A_f}}$	CAF	Orbiter forebody axial force coefficient.
$c_{A_{\mathbf{u}}}$	CAU	Orbiter axial force coefficient, uncorrected.
$C_{\mathbf{B}_{\mathbf{V}}}$	CBV	Vertical tail bending moment coefficient.
$^{\mathtt{C}}\mathbf{B}_{\mathtt{W}}$	CBW	Wing bending moment coefficient.
$c_{ m he_i}$	CHEI	Inner elevon hinge moment coefficient, about hinge line X = 1387.0.
$c_{h_{\mathbf{e_o}}}$	СНЕØ	Outer elevon hinge moment coefficient, about hinge line X = 1387.0.
cl	CBL	Orbiter rolling moment coefficient, body axis system.
c_{m_B}	CLMB	Orbiter base pitching moment coefficient.
C _m r	CLMF	Orbiter forebody pitching moment coefficient.
c_{m_u}	CLMU	Orbiter pitching moment coefficient, uncorrected
Cn	CYN	Orbiter yawing moment coefficient.
$c_{n_{\mathbf{V}}}$	CTV	Vertical tail yawing moment coefficient, using vertical tail reference.
c_{N_B}	CNB	Orbiter base normal force coefficient.
CN _f	CNF	Orbiter forebody normal force coefficient.
c_{N_u}	CNU	Orbiter normal force coefficient, uncorrected

NOMENCIATURE (Continued)

SYMBOL		DEFINITION
CN _w	CNW	Wing normal force (shear) coefficient.
$\mathtt{c}_{\mathtt{p_i}}$	CP(i)	Surface tap pressure coefficient, port i.
cs _▼	CSV	Vertical tail shear force coefficient using vertical references.
c_{T_W}	CTW	Wing torsion moment coefficient.
$c_{\mathbf{Y}}$	CY	Orbiter side force coefficient.
$\mathtt{H_{e_i}}$	-	Inboard elevon hinge moment, in-lbs.
Heo	-	Outboard elevon hinge moment, in-lbs.
M	MACH	Freestream Mach number.
Myt	-	Vertical tail normal (shear) force, lbs.
K	-	Wing normal (shear) force, lbs.
Pi	-	Pressure at surface tap i, psf.
Po	P	Freestream static pressure, psf.
Pt	PT	Freestream total pressure, psf.
q	Q(PSF)	Freestream dynamic pressure, psf.
	RN/L	Unit Reynolds number, million per foot
$\mathtt{T_t}$	TTF	Freestream total temperature, OR.
Tvt	- -	Vertical tail torsion moment, in-lbs.
T_W	-	Wing torsion moment, in-lbs.
α	ALPHAT	Angle-of-attack of the ET/SRB's, degrees.
αο	alphaø	Orbiter angle-of-attack, degrees.
β	BETAT	Angle-of-sideslip of the ET/SRB's, degrees
eta_{o}	вета ø	Orbiter angle-of-sideslip, degrees.

NOMENCLATURE (Continued)

SYMBOL		DEFINITION
δei	ELVRI	Right inboard elevon deflection, under air load, degrees.
$^{\delta}$ e $_{o}$	ELVRØ	Right outboard elevon deflection, under air load, degrees.
δ _{ei} /no load	ERI/ELI	Inboard elevon deflection, degrees preset (Right/Left).
$\delta_{e_0}/n0$ load	erø/elø	Outboard elevon deflection, degrees preset (Right/Left).
$^{\Delta\delta}$ eø	DØ	Elevon increment due to air load, ELVRØ-ERO.
$^{\Delta\delta}$ e _I	DI	Elevon increment due to airload, ELVRI-ERI.
	IB-ELV	Nominal inboard elevon setting - deg.
	ØB-ELV	Nominal outboard elevon setting - deg.
Ø	PHI	Angular cylindrical coordinate position around body - deg.
x/c _{BF}	X/CBF	Chordwise location on body flap, fraction of local chord.
x _o /L _o	X/LB	Longitudinal location on orbiter body surface, fraction of body length.
x_s/L_s	XS/LS	Longitudinal location on solid rocket booster body surface, fraction of body length.
x_T/L_T	XT/LT	Longitudinal location on external tank body surface, fraction of body length.
x_v/c_v	xv/cv	Chordwise location on vertical tail, fraction of local chord.
x_w/c_w	xw/cw	Chordwise location on wing surface, fraction of local chord.
Yo	YO	Orbiter base lateral centerline.

NOMENCLATURE (Concluded)

SYMBOL		<u>DEFINITION</u>
n_{BF}	Y/BBF	Spanwise location on body flap, fraction of body flap span.
$\eta_{\mathbf{v}}$	ZB/BV	Spanwise location on vertical tail, fraction of vertical tail span
$\eta_{\overline{\mathbf{W}}}$	Y/BW	Spanwise location on wing, fraction of semi-span
	AADS	Parametric value of rotation angle for AADS probes.
	GAPS	Parametric value of 1.0 indicates wing gaps sealed.
	SILTS	Parametric value - 1.0 indicates SILTS on and 0.0 indicates SILTS off.
$x_{CP_{\mathbf{v}}}$	XCPV	Vertical tail center-of-pressure, longitudinal location, in.
x_{CP_w}	XCPW	Wing center-of-pressure, longitudinal location, in.
$^{\mathtt{Y}}_{\mathtt{CP}_{\mathbf{v}}}$	YCPV	Vertical tail center-of-pressure, lateral location, in.
Y _{CP}	YCPW	Wing center-of-pressure, lateral location, in.

REMARKS

Test IA184 was conducted basically as planned during the period between April 6 and April 13, 1979. The model was installed in the tunnel during the week of March 19, however, a variety of computer and equipment problems delayed the test start date. All objectives of the test were accomplished.

The test was conducted as planned except as follows:

- 1. The pressure instrumented tail was removed and the force instrumented vertical installed prior to the completion of Configuration 17 rather than after. Therefore, runs 53, 55 and 56 are repeats of runs 48, 49, and 50, respectively, with the only change being the vertical tail.
- 2. There was no plan to run the "force" vertical with SILTS pod installed. However, this configuration was tested during runs 53 through 79.
- 3. Runs 104 through 109 repeat runs 93, 95, 97, 98, 100 and 102 with tape covering all metric gaps (except for the main balance). These runs were made to again determine the effects of the metric gap on the orbiter aerodynamic simulation.

During the test various events occurred having a possible effect on the test results. These items are listed below.

- 1. Pressure tap 688 had a slow leak for the entire test. It was moved from Scanivalve A-2, Port 12 to Scanivalve B-15, Port 29 prior to the test.
- 2. Pressure taps 573 through 576, on the top of the vertical tail, were measured on runs 4 through 50. These taps were connected to Scanivalve B-13, Ports 25 through 28, respectively.
- 3. Pressure taps 291 through 297 were added to the orbiter prior to the test. These taps are located as follows:

REMARKS (Concluded)

TAP NO.	<u>x</u> o	Yo	Zo	φ
2 91	1317.5	-106.6	363.5	71.1
292	1317.5	-106.8	402.0	91.1
293	1390.0	-113.4	334.3	59•9
294	1430.2	-117.5	334.6	60.9
295	1454.5	-118.9	360.5	71.6
2 96	1454.5	-117.0	402.6	91.3
297	1480.1	-122.7	332.9	61.3

- 4. During runs 20 through 24 no data were obtained from Scanivalve A-1 (see Reference 1 for affected pressure tap numbers).
- 5. Prior to run 43 the simulated GH_2 pressure line on the external tank was broken off aft of station X_T 1700 (full scale). This protuberance was missing during runs 43 through 50, after which it was repaired.
- 6. During runs 53 through 79 pressure taps 1392 and 1507 were plugged.
- 7. During runs 53 through 115 all vertical tail pressure taps (5xx numbers) were disconnected (force vertical tail was installed).
- 8. During runs 93 through 109, pressure tap 858 was plugged and 857 and 887 were leaking.
- 9. During runs 104 through 109 the following pressure taps were plugged: 182, 401, 409, 417, 425, 433 and 685.
- 10. Check loading of the wing (right hand) in the tunnel revealed that the wing fouled against the orbiter for negative values of torsion greater than 500 inch-pounds.

CONFIGURATIONS INVESTIGATED

The model for the MASA/Ames 9 x 7-foot tunnel test period was a 0.03-scale replica of the Rockwell International Space Shuttle Vehicle in launch configuration. The launch configuration consists of the assembly of a payload carrying orbiter, an expendable external oxygen/hydrogen tank (ET)(which provides fuel for the orbiter main engines), and two expendable solid rocket boosters (SRB's). The general layout of the model is shown in Figure 2a.

The orbiter is of blended wing body design with a double delta planform (81°/45° leading edge) 12% thick wing with full span elevons incorporating a six-inch interpanel gap between the independently deflectable inboard and outboard panels. A single swept (45°) centerline vertical tail with rudder and/or speed brake capability is mounted between two orbital maneuvering system (CMS) pods, and a single body flap (to aid in trim control while the speed brake is flared during re-entry) is fitted on the lower trailing edge of the fuselage.

The orbiter fuselage is in accord with Rockwell International control drawing VI70-000140A, with the vertical tail as defined by drawing VI70-000146A. The CMS pods are of the later VI70-000140C configuration, these being a combination of the VI70-08401 and VI70-08410 drawings. Fitted to this is a new orbiter vehicle 102 wing as defined in the MD-V70 data book(s). For the purposes of this test and report, this combination shall be referred to as a "102 orbiter" with the concurrence of the Aerodynamics Loads Group. The orbiter is shown in

Figure 2b.

The ET is of cylindrical cross section with a nominal diameter of 333.0 inches full-scale and a maximum diameter of 336.2 inches full-scale. The forward portion of the ET has a tangent ogive nose which terminates in a biconic nose cap over the LOX vent valve. The biconic nose has a pitot and two static pressure taps as a sensing part of the ascent air data system (AADS). The forward third of the tank is filled with LOX, and the aft two thirds is a vessel for liquid hydrogen. The aft end of the tank is basically an ellipsoid of revolution. Between the two vessels is a structure of stiffeners which is slightly larger than the nominal tank diameter. Covering the entire tank is a spray on foam insulation (SOFI) of varying thickness as dictated by the relative heat load, i.e., approximately 2.5 inches thick on the tangent ogive, 1.0 inch thick on the cylindrical portion of the tank and 2.0 inch thick on the rear ellipsoid. The diameters given above include this SOFI. Standing proud of this insulation are a number of external protuberances which fall into three major categories: electrical trays, fluid lines, and attach hardware. Electrical trays which run parallel to the centerline of the tank are simulated, those which run up next to the aft orbiter/ET attach hardware are not. Fluid lines modeled are the LOX and IH2 feed and vent plumbing. The attach hardware that is considered as part of the tank is the front and rear ET/orbiter attach structure, which is discarded with the KT at the end of the main engine burn.

The external tank is built to the geometry described above and more specifically to Rockwell International Interface Control Drawing ICD 2-00001, Rev. C, plus Interface Revision Motices B and C. The external tank is shown in Figure 2c.

The two solid rocket boosters (SRB's) are 146-inch nominal diameter cylinders, each with an 18-degree semi-angle nose with a 13.27-inch spherical tip. An 18-degree flared skirt, 208.20-inch diameter, protects the gimbaled rocket nozzle. A flexible, donut-shaped seal and thermal shield is provided between skirt and nozzle. Major protrusions from the basic envelope include a forward attach lug, separation thrusters front and rear, aft attach ring, various stiffeners and a full length electrical systems tunnel.

In common with the external tank, the SRB is built in accord with the Rockwell International Interface Control Document ICD 2-00001C, with the supplement of Interface Revision Notices B and C. An SRB is shown in Figure 2d.

The entire model was therefore basically in accord with the Configuration 6 Launch Vehicle, comprised of the 102 orbiter and T_{39} tank and S_{27} boosters.

The orbiter provided for this test series is constructed utilizing existing orbiter fuselage, vertical tail, CMS pods wing, and body flap components. An internal beam/bridge/balance block has been constructed to allow mounting the orbiter from the attach hardware of the ET and to

measure six component airloads on the orbiter. Safety factors of three (3) on yield and five (5) on ultimate have been observed. The complete orbiter weighs approximately 140 pounds. The model has been principally fabricated of 17-4 stainless steel and aluminum alloy with some contouring with Renite. The orbiter is fabricated around a control balance block of 17-4 bored and sleeved to accept the Task 2.5-inch MK XXII balance. This block is located in the rear half of the fuselage and the 7076 aluminum pieces which form the outer mold line of the fuselage are bolted to it. These pieces consist of a fuselage cover, two fuselage fairings and two wing fairings at the rear of the body, two side covers, and a forward nose and top cover. The two CMS pods are fabricated of 7076-T6 aluminum alloy and are secured to the aft top cover with 10-32 AHCS. The CMS nozzles are simulated in aluminum as are the RCS thrusters.

The wing is a two piece aluminum article screwed to a central stainless steel wing beam. This beam of cross shaped planform supports one wing on a tang on each side of the central plate. The right hand tang is instrumented with strain gauges to form the three component wing load indicator balance. While the center of this beam forms the outer mold line of the bottom of the orbiter, the tangs are of course, out of the airstream. The wings are made integral with the glove and a labyrinth seal is provided on the metric side to improve the data quality. The wings are extensively hollowed to reduce the model weight. The left

hand wing is instrumented with pressure taps. Each of the wings is fitted with deflectable inboard and outboard elevons which are supported in torsion only by a beam mounted on the hinge line, and in all other degrees of freedom by plain bearing hinges, also on the scale hinge line. Identical R.H. and L.H. elevon supports insure similar aeroelastic deflections. The opposite end of the elevon support beam is fitted with a ball bearing to minimize hysteresis effects. The right hand wing panels are supported on beams which are strain gauges. Available deflections are listed in Table III. For negative elevon deflections (T.E. up) simulated flipper doors are fitted to the upper wing surface.

An aluminum body flap with hinge moment capability and 40 pressure taps is provided. The panel is mounted with a single component Armco beam pinned to an Armco shaft and bracket. This bracket is attached to the ball bearing mounted Armco hinge shafts which support the panel in torsion. The remainder of the loads are carried on the hinges. The opposite, orbiter end of the flexture is supported in an Armco cavity through a single ball bearing to minimize hysteresis effects. Four pairs of holes between the body flap bracket and the hinge shaft allow for selection of one of the four of settings, -11.7, 0, +16.3 or +22.5 degrees. The hinge moment capability was not used, nor was the body flap deflection changed during this test entry.

Two vertical tails are provided for this test, the first being of 17-4PH Armco with a single plain hinged rudder/speed brake on each side.

These panels are individually pinned to the hinge shaft, the shaft is then pinned to the vertical. Five sets of hole pairs are provided between the panels and the shaft to provide speed brake settings. The entire shaft is then rotated and pinned to provide one of five rudder deflections; thus any combination of rudder/speed brake provided can be run. No rudder/speed brake deflections were used for this test. This is a pressure instrumented surface with 76 pressures (including one of the base group, #301). The hardline tubulations terminate at the front of the base of the tail, from whence the tubes are of flexible plastic to the Scanivalves. The tail itself is hard mounted to the balance block with six AHCS in a cavity at the upper rear of the fuselage.

The second vertical is of aluminum and mounts through this same cavity, but is supported on a balance to measure vertical tail airloads directly. The upper and lower halves of the left and right panels of the rudder are all separately hinged on ball bearings, with single flexure strain gauge beams supporting each panel in torsion about the hinge line. Panel deflections are set by changing brackets which are screwed to the rudder and pinned and screwed with 6-40 AHCS to the strain gauge beam. Again, the inner end of the steel beam is mounted in a steel pocket insert via a ball bearing to minimize hysteresis. This arrangement allows certain discreet $\delta_{\mathbf{r}}/\delta_{\mathbf{sb}}$ combinations only. The speed brake and rudder deflections remained at zero and rudder hinge moments were not measured during this test.

Simulated SSME nozzles are provided in the base of the orbiter, since no sting interferes. The nozzles are set at the nominal angles of 16 degrees up, no yaw upper, and 10 degrees up, $\frac{1}{3}$ 1/2 degrees yaw outboard for the lower two. The material used is aluminum alloy. The nozzles are mounted to a base plate which closes off the balance cavity at the back of the orbiter.

The entire orbiter is mounted on the balance mentioned, with the taper fitting into a block in the cavity at the rear of the fuselage mentioned above. This block is screwed to a beam running under the balance block and also to a stiffener rod that runs forward above the right corner of the balance block to a "flying wedge" piece attached to the right front of the longitudinal beam. The ET attach hardware mounts to the bottom beam through holes in the bottom of the orbiter.

The external tank is principally fabricated of aluminum alloy to reduce weight and fabrication costs. The approximate weight of the external tank with instrumentation is 190 pounds. Safety factors of three (3) on yield and five (5) on ultimate have been observed in the design and construction of the tank.

The 333-inch full-scale diameter tank is built up out of four principal shell-like pieces that conform to the outer mold line of the tank including the spray on foam insulation. These pieces are a nose which includes the entire tangent ogive (and is actually made up of two non-separable pieces because of a late lines change), a cylindrical mid-

body, a short cylindrical aft body, and an aft cap. Slipped around the back of the aft body to fair into the cap is a ring designated a recontouring block, and an .030-inch shim is placed beneath the cap. These last two items are also the result of a late lines change.

The nose is secured to the mid-body with 1/4-20 AHCS, and the joint from the mid to aft body is secured with 10-32 AHCS. The recontouring block is secured with 10-24 AHCS and the cap is fastened to the aft body with 1/4-20 AHCS. There are two holes aft and one hole forward on each side which are spotfaced inside and out to accept the SRB ring mounting study and screws.

Slipped into the front of the nose of the tank is a biconic went valve housing with an integral 10-degree half-angle conical yaw probe at the front. This yaw probe (The Ascent Air Data System or AADS) is instrumented to scale with two .010-inch OD hypodermic tubing taps at the scale location, .075-inch aft of the tip of the spike (taps 1901 and 1902).

The orbiter/ET attach hardware is scaled to as great a degree possible and is load bearing. The orbiter/ET front attach was originally fabricated from a single piece of 17-4 stainless steel with two end plates, but prior to testing was modified to prevent orbiter rolling moment from being transmitted to the structure by use of a pin joint at the orbiter. The lower end plate fits into a milled recess in the ET mid-body and is secured with 10-32 AECS; the upper one fitting into an

analagous recess in the orbiter, and using 5/16-24 AHCS to fasten it to the orbiter balance beam.

The aft load is carried through the vertical runs of the IO₂ and IH₂ feed lines, which are bushed, hollow bolts securing the ET to the orbiter balance block. The simulated aft ET/SRB attach hardware is of stainless steel and does not carry load.

Detailed external tank protuberances are provided and these are fabricated of 17-4 stainless and are secured by 3-48 FHCS holding integral mounting buttons into recesses in the tank. The pressure and feed lines are as previously used on model 47-T on the 331-inch tank, the ellipsoid fairings and cable trays are of necessity new construction.

The finer details of this plumbing and the attachment of the button are accomplished with silver solder. Scanivalve and balance cables and pressures are routed into the tank from the orbiter through the hollow rear attach bolts (1/4-inch I.D.) and these and the cables from the tank Scanivalves are led out to the SRB's just behind the SRB front attach. The entire tank and it's protrusions are pressure instrumented.

The two aluminum SRB's are reworked from a previous usage with the principal alterations being to the protuberances, the number of pressure taps (added to reflect the requests of the customer), and the mode of attaching the SRB to the ET. The SRB to ET attachments were modified to bear the expected loads and to carry the electrical leads through from the tank.

The SRB's are fabricated of 2024-T4 aluminum alloy to reduce weight. The weight of the right hand SRB is approximately 40 pounds and the weight of the thinner, left hand SRB with the Scanivalves is approximately 21 pounds. Safety factors of three (3) for yield and five (5) for ultimate have been observed in this design.

Both SRB's are built around a 2.00-inch I.D. x 3.38-inch O.D. aluminum sleeve. This sleeve is to be pinned to the eccentric adapter and to the body of the SRB with two 1/4-inch pull pins on each side. The SRB itself consists of four main parts, a nose cone, a forebody, an aft attach ring and an aft body and nossle assembly.

The SRB's are built up around the forebody with all instrumentation installed and are then slipped into the mounting holes in the tank. The aft body, spacer skirt, nozzle and thermal protecting shield of 2024 aluminum alloy are assembled with 2-56, 6-32 and 8-32 ARCS and installed as a unit on the forebody, sandwiching the 17-4 stainless steel aft attach ring between them. This ring is carved of a single piece of stock with integral different size mounting study that simulate the aft attach struts, the study being threaded on the inboard end.

A 7/16 AHCS passes through the simulated SRB/ET front attach to secure the front of the SRB to the ET, the nuts for this bolt and the two rear studes are inside of the ET. The nose cone, which is of 2024 aluminum alloy, slips over the forebody of the SRB after the booster is secured to the external tank, and is fastened with four 6-32 AHCS.

Mozzle actuator struts are simulated on each of the SRB aft skirts. The SRB aft separation thrusters are of aluminum alloy and are attached to the skirt with 6-32 AHCS and locating pins. The cable tunnel is of aluminum alloy and is secured with 2-56 AHCS. The skirt stiffeners are of aluminum alloy and are both bonded and attached with 1-64 FHCS. The SRB stiffener rings (4) are of 17-4 stainless steel and are split to fit over the skirt and snap into a locating groove. They are secured by filling the remainder of the groove with Renite, an epoxy filler resin. The forward attach lug, just aft of the ET lug with the 7/16-inch securing screw, is hollowed out to provide a 3/8-inch x 3/4-inch passage for instrumentation leads.

The left hand SRB is instrumented with pressure taps and a multiple Scanivalve unit. To provide access to the valves, a cover is fit to the IH forebody and is secured with 6-32 AHCS. All reference pressures, and instrumentation leads from the SRB are run internal to the IH fork of the sting.

The following nomenclature, illustrated in Figures 2b through 2d, was used to designate the model components:

Symbol	Description	
B ₆₂	-140 A/B Body	
c 9	-140 A/B Canopy	
^Е 64	OW 102 Elevon	
W ₁₃₁	OV 102 Wing	

Symbol	Description
M ₁₆	Short CMS pods, -140 C w/nozzles
N ₁₁₂	SSME nozzles, OV102 complete
R 5	146 A Rudder
v ₈	146 A Vertical Tail
FD3	Flipper Doors
A configuration code has not been assigned for the SILTS pod.	
T 39	External Tank complete 330-inch O.D. with protuberances
^S 27	Solid Rocket Booster complete 146-inch O.D. with protuberances

TEST FACILITY DESCRIPTION

This tunnel is one of the supersonic legs of the Ames Unitary facility. It is a closed circuit, variable density, continuous flow tunnel. The test section is 9 feet by 7 feet by 18 feet and the nozzle is of the asymmetric, sliding-block type in which the variation of the test section Mach number is achieved by translating, in the streamwise direction, the fixed contour block that forms the floor of the nozzle. The temperature in all three circuits is controlled by after-cooling. Dry air for use in the circuit is supplied from four 30,000 cubic-foot spherical tanks. The tunnel drive motors and compressor also serve the 8 by 7-foot tunnel. The motors have a combined output of 180,000 horsepower for continuous operations or 216,000 horsepower for one hour.

TEST PROCEDURE

The model was mounted upright in the tunnel on a steel forked sting supplied by Rockwell International. This sting was mounted to a primary taper adapter supplied by Ames Research Center and built by General Dynamics, Fort Worth. This adapter, through a system of arms and pivots, is designed to maintain the model in the center of the tunnel during angle-of-attack sweeps.

The model was instrumented so that pressure and force data could be obtained simultaneously, except on the vertical tail where both pressure instrumented and force (strain gauge) instrumented vertical tails were used. In general, only those model pressures were recorded which are aft of orbiter model Station $X_0 = 33$ (model scale). This corresponds with ET Station $X_T = 55.23$ and SRB Station 38.94. Pressures on the AADS probe (only taps 1901 and 1902), ET 40 degree cone taps 1010, 1012, 1014, and 1016 at X/LT = 0.02 (Phi = 0, 90, 180, and 270°, respectively), and some of the pressures on the attach structure and protuberances were also measured. Figures 2e through 2p and Tables IV and V give the locations of the measured pressures.

All model pressures were measured using four gangs of Scanivalves mounted in the various elements of the model. Information on the Scanivalve installations and the pressure tap assignments to each valve are given in Reference 1, with any changes denoted in the Remarks section of this report.

The orbiter was mounted on the ET by means of the AEDC/PWT MK XXII 2.5-inch Task balance. The existing suspension system and balance sleeve for the MK XXXI balance (same dimensions as the MK XXII) were used.

TEST PROCEDURE (Continued)

The right hand wing was mounted on a single beam three-component balance which supports the panel in all degrees of freedom. Two bending moment and one torsion moment flexures were provided. The metric gap was fitted with a labyrinth seal and fouling indicator. A thin strip of low density foam was installed in the metric gap to minimize airflow through the gap. Due to an electrical problem, the fouling indicator was not operational during the test.

The previously manufactured dummy balance used with the "force" vertical, has been machined and gauged to form a four component balance. The balance has two yawing moment (side force) gauges, one roll (torsion) gauge and one pitching moment gauge. The sole purpose of the pitching moment gauge is to allow for the determination of interactions due to axial forces acting on the vertical tail. The initial configuration included the pressure instrumented vertical. "Quick-disconnect" plugs in the pressure tubing were used to permit a rapid change from the "pressure" to the "force" vertical tail.

The right hand elevons were instrumented to measure hinge moment directly via a beam that supports the panel in torsion about a hinge line coincident with the scale hinge line. Thus, the output of the strain gauge bridge was directly proportional to the applied moment. Deflection angles used for this test are given in Table III.

An ARC-supplied angular position indicator (dangleometer) was mounted in the external tank, and was used to position the model in pitch

TEST PROCEDURE (Continued)

during the test.

The pressure transducers were not calibrated prior to the test but were check calibrated after the model was installed in the tunnel using the "reference" and "calibrate" ports on the Scanivalves in accordance with normal ARC procedures.

After installation all pressures were either leak checked using a hand-held vacuum pump or continuity checked with shop air when the orifice was located in a position where it could not be leak checked. Leak checks were performed during model changes to check all pressures which had been disconnected during the model change.

The 2 1/2-inch MK XXII balance and the vertical tail balance were calibrated in the ARC calibration laboratory prior to the test. The wing calibration used for test OAl46 was used for this test. The elevon hinge moment gauges were calibrated in the tunnel after the model was installed, and were check calibrated after each change in elevon angle. All balances were check-loaded after the model was installed in the tunnel.

After installation in the model the dangleometer was calibrated over the angle-of-attack range required for the test.

The general test procedure was as follows: After starting the tunnel the desired test conditions for a particular Mach number (the lowest required for the subject configuration) were established as given in Table I. The tunnel horizontal strut was then positioned to give the required angle-of-sideslip and the model was then pitched through the

TEST PROCEDURE (Concluded)

angle-of-attack range called for in the run schedule using the General Dynamics articulated sting. Data were obtained during a pause at each required angle-of-attack. After data were obtained in this manner at all angles-of-sideslip at a particular Mach number, the test conditions were changed to the next higher Mach number and the process was repeated. After all data on a particular configuration had been obtained, the tunnel was shut down for a model change to the next scheduled elevon setting. Periodically, the AADS probe was rotated in 90-degree increments so that data were obtained on the AADS pressure taps in four different positions. The change from the "pressure" to the "force" vertical tail was made during the non-running shift to provide sufficient time to check out the balance. The SILTS pod was also removed during a non-running shift to minimize model change time during the running shift.

DATA REDUCTION

Standard ARC methods for computing tunnel parameters, balance forces and moments, and model attitudes were used. Pressure coefficients were calculated for all model pressures. Force and moment coefficients (body axis system only) were computed for each balance using the axis system defined in Figure 1a. Orbiter force and moment data were adjusted to account for the difference between measured base pressure and freestream pressure. Elevon hinge moments, and wing and vertical tail forces and moments were calculated in coefficient form about reference locations specified for each component.

The moment reference locations, in full-scale dimensions, are as follows:

Total vehicle

(Used for orbiter data): X_T 976, Y_T0, Z_T 400

Right wing:

Xo 1307, Yo 105

Right elevons:

Hingeline at X₀ 1387

Vertical tail:

X₀ 1414.3, Z₀ 503

The attitude of the external tank/SRB's was calculated from the sector reading and the output of the dangleometer mounted in the external tank. Balance deflections were accounted for in determining the attitude of the orbiter. The deflection of the elevons and the vertical tail due to applied loads was also calculated. The deflection of the wing under load was found to be insignificant and therefore was not accounted for in data reduction.

Pressure coefficients were computed as follows:

$$c_{p_4} = (P_1 - P_0)/q$$

where "i" represents the model orifice number.

Standard six component body axis force coefficients were computed for the balance mounted orbiter. The reference area used was the orbiter wing area, and the reference length for moment coefficients was the orbiter reference length. Moments were computed at the integrated vehicle reference center which is at the orbiter nose on the tank centerline. This is located at $X_T = 976$, $Y_T = 0$, $Z_T = 400$ in tank coordinates, and $X_O = 235$, $Y_O = 0$, $Z_O = 63.5$ in orbiter coordinates. The balance transfer dimensions are depicted in Figure 1c.

The normal force, axial force, and pitching moment coefficients for the orbiter were adjusted for base pressure as follows:

$$C_{N_B} = \frac{-1}{S_W} \tan 14.75^{\circ}$$
 $\sum_{301}^{324} C_{p_1} A_1 + \frac{-1}{S_W} \sum_{401}^{440} C_{p_1} A_1$

$$c_{A_B} = \frac{-1}{S_W} \sum_{301}^{324} c_{p_1 A_1}$$

$$c_{m_B} = \frac{-1}{S_w b} - X_1 \tan 14.75^{\circ}$$
 $\sum_{301}^{324} c_{p_i} A_i - X_2 \sum_{401}^{440} c_{p_i} A_i + Z_1 \sum_{301}^{324} c_{p_i} A_i$

where x_1 , x_2 and z_1 are the distances to the centroid of the area from the moment reference center.

The resulting coefficients are applied as follows to obtain the forebody coefficients:

The model component loads were reduced to force and moment coefficients in the following manner:

For wing bending and torsion: (See Figure 1d for wing MRC)

$$C_{N_W} = N_W/[(q)(S_W)]$$

$$C_{B_W} = B_W/[(q)(S_W)(b_W)]$$

$$C_{T_W} = T_W/[(q)(S_W)(\overline{c})]$$

For wing center-of-pressure:

$$X_{CP_w} = 1307 - \frac{C_{T_w}}{C_{N_w}} - \frac{\bar{c}}{0.03}$$

$$Y_{CP_w} = 105 + \frac{C_{B_w}}{C_{N_w}} \frac{b_w}{0.03}$$

For vertical tail bending and torsion: (See Figure le for VT MRC)

$$C_{S_v} = W_{vt}/[(q)(S_{vt})]$$

$$C_{B_v} = B_{vt}/[(q)(S_{vt})(C_{vt})]$$

$$C_{n_v} = T_{vt}/[(q)(S_{vt})(C_{vt})]$$

(Data from the vertical tail pitching moment gauge were not reduced.)

For vertical tail center-of-pressure:

$$X_{CP_v} = 1414.3 - \frac{Cn_v}{Cs_v} \cdot \frac{C_{vt}}{0.03}$$

$$Y_{CP_{v}} = 503 + \frac{C_{B_{v}}}{C_{s_{v}}} \cdot \frac{C_{vt}}{0.03}$$

For elevon hinge moments:

$$C_{\text{he}_{i}} = H_{e_{i}}/[(q)(S_{e})(C_{e})]$$

$$c_{\rm h_{\rm e_o}} = {\rm H_{\rm e_o}}/{\left[(\rm q)\,(\rm S_e)\,(\rm C_e)\right]}$$

A schedule of completed runs is given in Table II which is the Data Set/Run Number Collation Summary for the test.

Reference dimensions and constants used were:

SYMBOL	MODEL SCALE	FULL SCALE	DESCRIPTION	
A ₃₀₁	- 0 -		Orbiter base area for pressure tap	301
A ₃₀₂	0.022146 ft. ²			302
A ₃₀₃	0.122387			303
A304	0.005970			304
A ₃₀₅	0.004909			305
A306	0.009287			306
A307	0.007960			307
A308	0.010613			308
A309	0.022554		↓	309

SYMBOL	VALUE MODEL SCALE	FULL SCALE	DESCRIPTION	
A ₃₁₀	0.003980		Orbiter base area for pressure tap 31	10
A ₃₁₁	0.023217		31	11
A ₃₁₂	0.016584		31	12
A ₃₁₃	0.001327		33	13
A ₃₁₄	0.011940		33	14
A ₃₁₅	0.013798		3:	15
A ₃₁₆	0.007297		3:	16
A ₃₁₇	0.012603		3:	17
A ₃₁₈	0.017247		3	18
A ₃₁₉	0.021758		3	19
A ₃₂₀	0.015920		3	20
A ₃₂₁	0.017247		3	21
A ₃₂₂	0.014328		3	22
A ₃₂₃	0.006103		3	23
A ₃₂₄	0.026003		3	24
A ₄₀₁	- 0 -		Body flap base area for pressure tap 4	01
A ₄₀₂	- 0 -		4	02
A ₄₀₃	- 0 -		4	03
A ₄₀₄	- 0 -		4	04
A ₄₀₅	0.01151 ft. ²		4	05
A ₄₀₆	0.010267 ft. ²		4	106
A ₄₀₇	0.0089838 ft. ²		. 4	07

	VALUE			
SYMBOL	MODEL SCALE	FULL SCALE	DESCRIPTION	
A408	0.0077004 ft.		Body flap base area for pressure tap	408
A409	- 0 -			409
A ₄₁₀	- 0 -			410
A ₄₁₁	- 0 -			411
A 412	- 0 -			412
A413	0.012834 ft. ²			413
A414	0.012834 ft. ²			414
A415	0.012834 ft. ²			415
A416	0.012834 ft. ²			416
A417	- 0 -			417
A418	- 0 -			418
A419	- 0 -			419
A420	- 0 -			420
A421	- 0 -			421
A422	- 0 -			422
A423	- 0 -			423
A424	- 0 -			424
A425	- 0 -			425
A426	- 0 -		4	426
A427	- 0 -		4	427
A428	- 0 -			28
A429	- 0 -		4	29
A430	- 0 -		†	30

	VALUE			
SYMBOL	MODEL SCALE	FULL SCALE	DESCRIPTION	
A ₄₃₁	- 0 -		Body flap base area	
			for pressure tap	431
A432	- 0 -			432
A ₄₃₃	- 0 -			433
A434	- 0 -			434
A ₄₃₅	- 0 -			435
A ₄₃₆	- 0 -			436
A ₄₃₇	.011551 ft. ²			437
A ₄₃₈	.010267 ft. ²			438
A ₄₃₉	.0089838 ft. ²			439
A ₄₄₀	.0077004 ft. ²		↓	440
b	38.709 in.	1290.3 in.	Orbiter reference 1	ength
$b_{\mathbf{w}}$	28.101 in.	936.7 in.	Wing bending refere	nce length
ō	14.244 in.	474.8 in.	Mean aerodynamic ch	ord
c_e	2.721 in.	90.7 in.	Elevon reference cho	ord length
c _{vt}	5.994 in.	199.8 in.	Vertical tail reference length	ence chord
s _e	0.189 ft. ²	210.0 ft. ²	Elevon reference are	ea .
s_w	2.421 ft.^2	2690. ft. ²	Wing reference area	
$s_{ extbf{vt}}$	0.3719 ft.^2	413.25 ft. ²	Vertical tail refere	ence area
x ₁	37.890 in.		Base pressure transf distance	er
x ₂	39.890 in.		Base pressure transi distance	er
$\mathbf{x_T}$	-25.570 in.	-852.33 in.	Longitudinal transfe from orbiter balance point to integrated	reference

DATA REDUCTION (Concluded)

	VALU	E	
SYMBOL	MODEL SCALE	FULL SCALE	DESCRIPTION
x _{TV}	2.341 in.	78.03 in.	Longitudinal transfer distance from vertical tail balance reference center to vertical tail MRC
z_1	9.795 in.	-326.5 in.	Base pressure transfer distance
${\sf z}_{ m T}$	-9.795 in.	-326. 5 in.	Vertical transfer distance from orbiter balance center- line to integrated vehicle MRC
z _{tv}	0.632 in.	21.07 in.	Vertical transfer distance from vertical tail balance centerline to vertical tail MRC

REFERENCES

- 1. STS-79-0016, "Pretest Information for Test IA184 of the 0.03-Scale Pressure Loads Model 47-0TS of the Space Shuttle Integrated Vehicle in the 9 x 7-Foot Supersonic Test Section of the Unitary Plan Wind Tunnel at Ames Research Center," dated March 5, 1979.
- 2. SD77-SH-0227, "Pretest Information for Test IA105B of the 0.03-Scale Pressure Loads Model 47-OTS of the Space Shuttle Integrated Vehicle in the 9-Foot by 7-Foot Supersonic Test Section of the Unitary Plan Wind Tunnel at NASA/Ames Research Center," dated October 12, 1977.
- 3. "Research Facilities Summary, Volume II Wind Tunnels: Subsonic, Transonic, Supersonic," NASA/Ames Research Center, dated December, 1965.

TEST: IA184			DATE: April 1979
	TEST CON	IDITIONS	
	·		
MACH NUMBER	REYNOLDS NUMBER (per foot)	DYNAMIC PRESSURE (pounds/sq.ft.)	STAGNATION TEMPERATURE , (degrees Fahrenheit)
1.55	3.5 x 10 ⁶	7 85	120
1.8	3.5 x 10 ⁶	790	120
2.2	3.5 x 10°	760	120
2.5	3.5 x 10 ⁶	710	120
BALANCE UTILIZED:	AEDC/PWT MK XXII	2.5-INCH TASK	
	CAPACITY:	ACCURACY:	COEFFICIENT
	•		TOLERANCE:
NF	5,000 lbs	±.5%	
SF	800 lbs		
AF	<u> </u>		
PM	4,000 in-lbs		
RM YM			
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90		α			ς'δ	6				30	8	33	75	n v	
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* * REFER TO PAGE 4 FOR COEFFICIENT SCHEDULES

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TABLE II. (Continued)

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		6	511	901	601															7		. (7)	1
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TABLE II. (Concluded)

DATASET/RUN NUMBER COLLATION SUMMARY

		CLMF	CLMB		DI	CP1902														
		CAF	CNB		00	CP1901														
		CNF	CAB		ERI	CP1016														
	I.E	CBL	YCPW		ERØ	CP1014														
	T SCHEDU	CXN	XCPW		ELI	CP1012														
	FORCE DATA COEFFICIENT SCHEDULE	CX	CBW	ZCPV	ELØ	CP1010														
	DATA CO	CLMU	CTW	XCPV	ELVRØ	Q(PSF)	- 1											ANCES		
	FORCE	CAU	CNW	CBV	ELVRI	Д	URE DATA COMPONENT	<u>p</u>	1			FOM		SURFACE	SURFACE		LEFT SRB	PROTUBER	CES	
		CNU	BETAT	CLV	$che\phi$	PT	E DATA	CHICET AC	A FUSELMA	BASE	AP, TOP	.AP, BOT	AL TAIL	3 UPPER 8	3 LOWER	AL TANK	RB	AL TANK]	OTUBERAN	ILSCELLANEOUS
		MACH	ALPHAT	CSV	CHEI	RN/L	PRESSUE	ODDITUEL	ONDITE	ORBITER	BODY FI	BODY FI	VERTIC/	LH WINC	LH WINC	EXTERN/	LEFT SI	EXTERN/	SRB PRO	MISCEL1
IDENT ABLE	SECOND	ALPHAØ	ALPHAØ	ALPHAØ	ALPHAØ	ALPHAØ		AT DUAG			ALPHAØ							ALPHAØ	ALPHAØ	ALPHAØ
INDEPENDENT VARIABLE	FIRST	BETAØ	BETAØ	BETAØ	BETAØ	BETAØ		DETAG	DEIAW	BETAØ	BETAØ	BETAØ	BETAØ	BETAØ	BETAØ	BETAØ	BETAØ	BETAØ	BETAØ	BETAØ
DATASET IDENTIFIER	1st CHARACTER	ы	Ţz.,	H	Ω	Λ	4th CHARACTER	æ	q	ъ	ტ	ſΞ	Λ	Ω	Ļ	₽	S	¥	Z	, ,

TABLE III. ELEVON DEFLECTION ANGLES

INBOARD	ELEVON ANGLES	, DEGREES
NOMINAL	LEFT HAND MEASURED	RICHT HAND MEASURED
12	12.45	12.60
10	10.58	12.60
8	8.32	8.45
4	4.45	4.58
0	0	0

CUTBOARI	FLEVOR ANGLE	s, degrees
NOMINAL	LEFT HAND MEASURED	RIGHT HAND MEASURED
+2	2.23	2.42
o	0	o
-2	-1.78	-1.72
- 5	-4.98	-4.98
-7	-6.88	-6.82

TABLE IV. MODEL 47 ORBITER FUSELAGE PRESSURE TAP ASSIGNMENTS

	BITER ATION				φ -	- RAJ	DIAL	LOCA	TIO	¶ ~ I	DEGR	ees			
FULL	X'o/Lo	0	20	40	70	82	90	105	110	120	135	150	165	180	Σ
1129	.6929					161									1
1215	• 7 595	162		163	164		165	166		167	168	169	170	171	10
1300	.8254	173		174	175		176	177		178	1 7 9	180		181	9
1318	.8393								218	219	220	221	222		5
1360	.8641								223	224	225	226	227		5
1375	.8835	183		184	185		186	187		188	189	190	191	192A	10
1390	.8951				193										ı
1430	.9261	194		195	196		197	198		199	200	201	202	203A	10
1455	-9455			·									21 2 A	213A	2
1480	.9649	204		205	206		207	20 8		209	210	211	212		9
15 3 0a	1.0036								214	215					2
1530ъ	1.0036								216	217					2
1548*	1.018	409	417	433											3*
1580*	1.043	410	418	434											3*
1609 *	1.0648	411	419	435											3*
1613*	1.0680	412	420	436											3*
		······································				<u>-</u>							;	LATO	78*/66

NOTES: $L_0 = 1290.3$ Inches

Taps 214, 215 Inside Base Region

^{*} Also Included in Body Flap Table

TABLE V. MODEL 47 EXTERMAL TANK BASE PRESSURE TAP ASSIGNMENTS

							•	A	E G R E	E S						
RADIUS FULL SCALE	0	15	30	54	9	8	112.5	135	157.5 180	180	202.5 225	225	247.5	570	38	330
166.5 (Tank)														د		
156.56	1502		1503	1501	1504	1505	1506	1507	1508	1509	1510	1511	1518	1513	1514	1515
टा.84ा	1516		1517		1518	1519	1520	1251	1522	1523	1524	1525	1526	1527	1528	1529
139.02	1530	1531	1531 1532	1533	1534	1535	1536	1537	1538	1539	1540	1541	1542	1543	1544 1545	1545
105.09	1546		1547		1548	1549 1550	1550	1551	1552	1553	ħ55T	1555	1556	1557	1558	1559
77.48	1560		1561		1562	1563	1 951	1565	1566	1567	1568	1569	1570	1571	1572	1573
0	1574															

TABLE VI. BAD PRESSURE DATA LIST (IA184)

						,						
PRESSURE TAPS		433,434,435 294,297 185,206	216 188,217 ALL 417,418,419 225,210		630,631,633,638	663,665 667,668,669,670	663,664,665 703,704,705, 706	738 768,769,770 799,800,801,802 831,832,833	861,862,863	51	714,715,716,717,718 744,745,746,747,748 774,775,776,777 779,780	
GEOMETRY 2	PHI	40 60 70	110 120 ALL 20 135	Y/BW	0.299	0.342	0.342 0.427	0.534 0.619 0.726 0.811	0.897 Y/BW	0.299	0.427 0.534 0.619 0.619	
GEOMETRY 1	X/LB	1.018 to 1.065 0.926, 0.964 0.884, 0.965	1.0 0.884, 1.0 ALL 1.043 to 1.065 0.864, 0.965	XW/CW	0.55,0.7,0.836,	0.4, 0.7 0.809 to 0.895	ALL 0.4,0.55,0.7 0.868 to 1.0	1.0 0.902 to 1.0 0.841 to 1.0 0.888 to 1.0	to]	0.7, 0.866	0.55 to 0.824 0.25 to 0.738 0.08 to 0.4 0.673 to 0.725	
ALPHA		3.666	-6.303		-2.451		-6,303 -6.215			-2.451		
ВЕТА		0.126	-6.040		-6.352	0.126	4.776			-6.352		
DATASET		R3KB07	R3KB08 R3KB19		R3KU04	R3KU07	R3KU19			R3KL04 R3KL07		
COMPONENT	FUSELAGE			WING, UPPER					WING, LOWER			
 				 	 		48	· · · · · · · · · · · · · · · · · · ·				

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TABLE VI. BAD PRESSURE DATA LIST (Continued) (IA184)

COMPONENT	DATASET	BETA	ALPHA	GEOMETRY 1	GEOMETRY 2	PRESSURE TAPS
WING, LOWER (cont.)				XW/CW	Y/BW	
				0.05 to 0.25 0.05 to 0.25	0.726	805,806,807,808 836,837,838,839
				0.05 to 0.642	0.897	866,867,868,869,870,871,872
	R3KL08	-6.040	-6.303	0.08 to 0.4	0.534	896,639,300,301,302,303,304 742,743,744,745
				0.906 to 1.0	0.534	752,753,738
	R3KL08	06.040	-6.303	0.953 to 1.0	0.619	785,770
				0.05 to 0.25	0.726	805,806,807,808
	R3KL19	4.776	-6.215	0.862	0	183
				0.862	0.226	184
		-		0.911 to 1.0	0.299	653,654,655,639
			<u>-</u>	0.25,0.758,1.0	0.427	712,716,706
				0.01,0.4,1.0	0.619	777.177
				0.01,0.02,0.05,	0.726	803,804,805,802
				ט.ו	ננס ס	020 020
			-	0.02 to 0.642	0.811	834,833 865 866 867 868 869 870 871 872
				1.0	0.897	863
				0.08 to 0.848	0.961	896,897,898,899,900,901,902,903,904
VERTICAL TAIL				xv/cv	\8/8Z	
	R3KV08	-6.040	6.303	ALL	9.0	554,555,556,557,558,559,560,561,562
				0 to 0.52 0.15,0.3,0.85	0.919	563,564,565,566,567,568 572,573,576
BODY FLAP, TOP				X/CBF	Y/88F	
	R3KG 01 R3KG03	0.500	-5.293	0.95 0.95	0.8	432 424 432
						101817

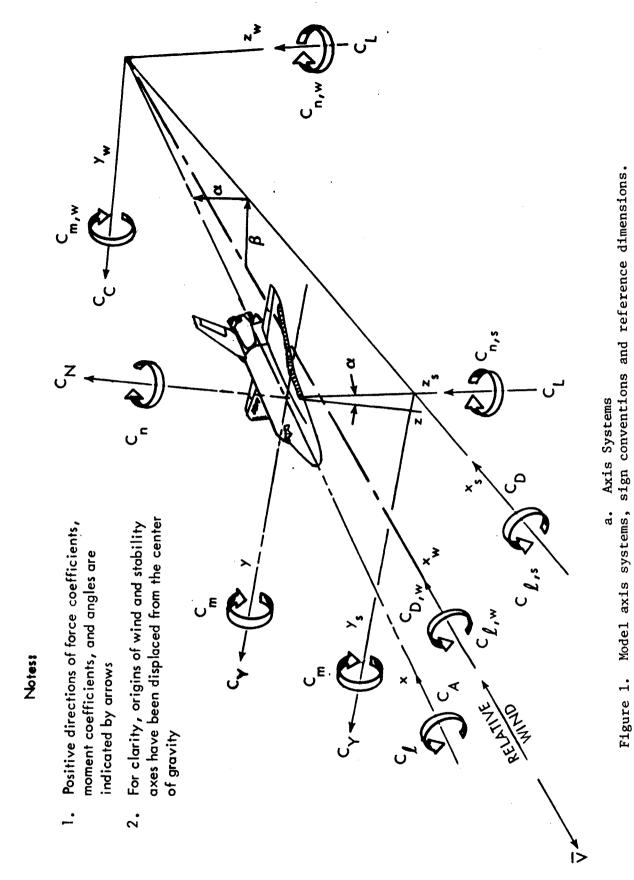
TABLE VI. BAD PRESSURE DATA LIST (Continued) (IA184)

PRESSURE TAPS				433,434,435,436 ALL 419,420 425,426,427,428		1562 1507,1510,1511 1422 1398,1411,1424 1386,1399,1412,1425 1018,1400,1530,1574 1388,1414,1503,1517,1532 1021,1416 1510,1511 1502,1503 1568,1566,1567
		421 406 405 ALL		433,43 ALL 419,42 425,43		(
GEOMETRY 2	Y/BBF	0.65 0.10 0.10 ALL	Y/BBF	0.9 ALL 0.65 0.8	РНІ	60 135,202,225 247 300 330 0 0 157 202,225 270 60,30 60,90,112.5 135,157.5,
GEOMETRY 1	X/CBF	-0.10 0.15 -0.10	X/CBF	ALL ALL 0.6,0.95 -0.1,0.2,0.6,	l .	0.992 0.956 0.931 0.863 to 0.931 0.031,0.896, 0.97,1.0 0.031, 0.931 0.931 0.956 0.031 0.956 0.985
ALPHA		3.972 3.972 -2.568 -6.303		3.666 -6.303 -6.215		3.666 -6.303
BETA		0.124 0.124 4.559		0.126 -6.040 4.776		0.126 -6.040 4.776
DATASET		93,608		R3KF07 R3KF08 R3KF19		R3KT07 R3KT08 R3KT19
COMPONENT	BODY FLAP, TOP (cont.)		BODY FLAP, BOTTOM		EXTERNAL TANK	

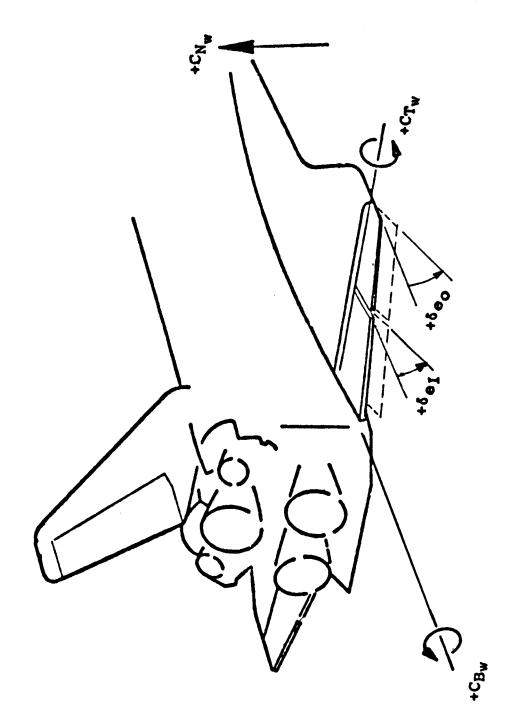
TABLE VI. BAD PRESSURE DATA LIST (Continued) (IA184)

TABLE VI. BAD PRESSURE DATA LIST (Concluded) (IA184)

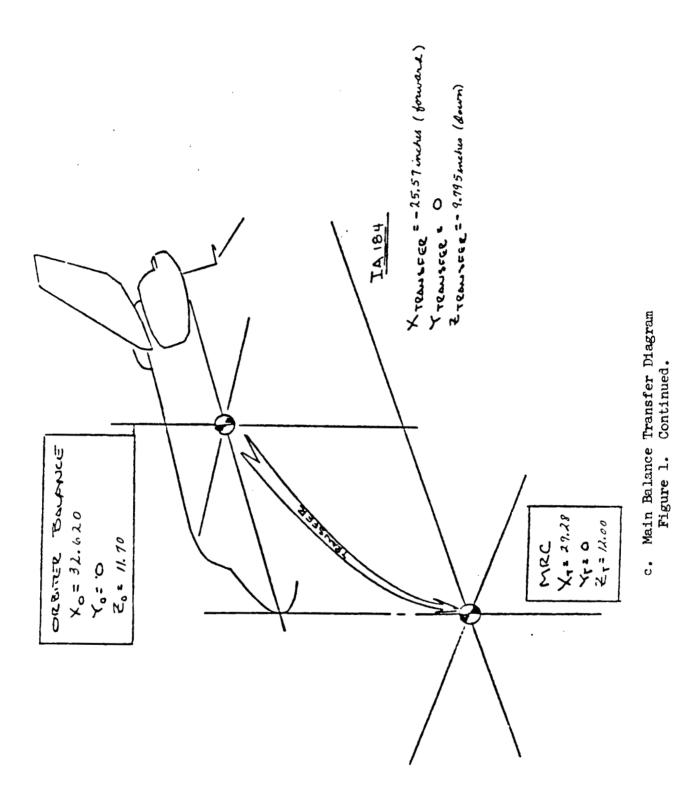
PRESSURE TAPS		312,316	302,303,320 ALL	301,302,308	319,320,321,322,323,324		1724,1769 1766		2356,2350		ALL ALL 214			
GEOMETRY 2	N/A	1 1	1 1	•	ı	N/A		N/A	•	N/A	111	•		
GEOMETRY 1	N/A	, ,			ŀ	N/A	1 1	N/A	١	N/A				
ALPHA		1.754	-6.303	ALL	-6.215		3.666		3.666		3.666 -6.303 -6.215			
BETA		0.146	-6.040	ALL	4.776		0.126		0.126		0.126 -6.040 4.776			
DATASET		R3KE03	R3KE08	R3KE10	R3KE21 R3KE19		R3KM07 R3KM08		R3KN07		R3KJ07 R3KJ08 R3KJ19			
COMPONENT	ORBITER BASE (cont.)					ET PROTUBERANCES		SRB PROTUBERANCES		MISCELLANEOUS				

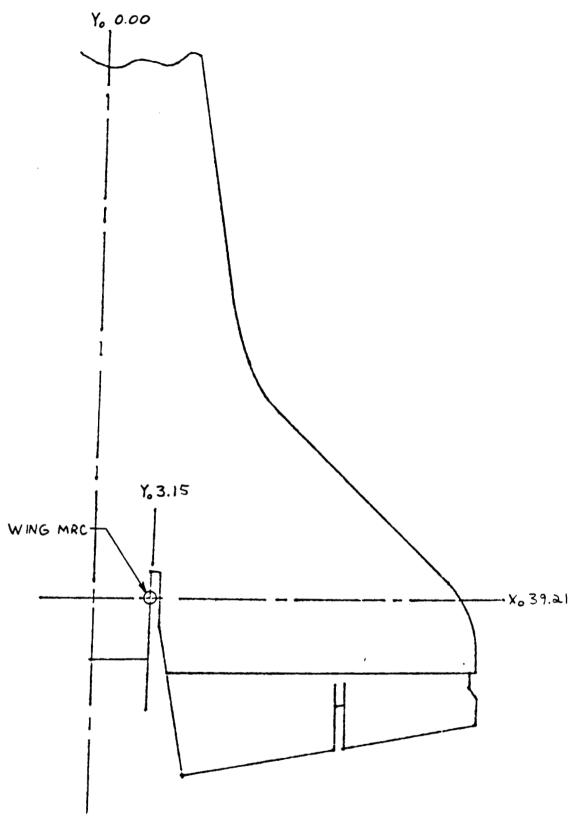


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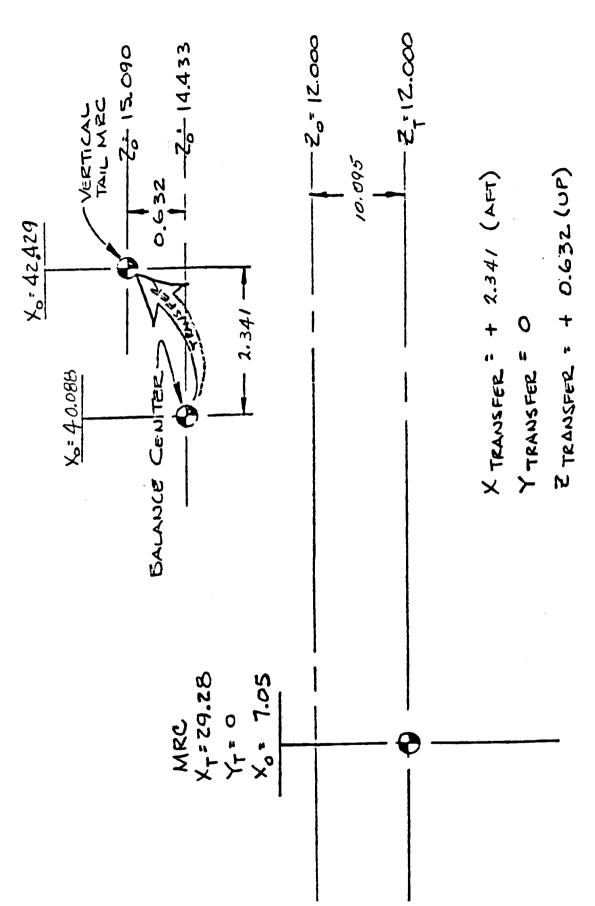


b. Definition of Deflection Angles and Wing Coefficients Figure 1. Continued



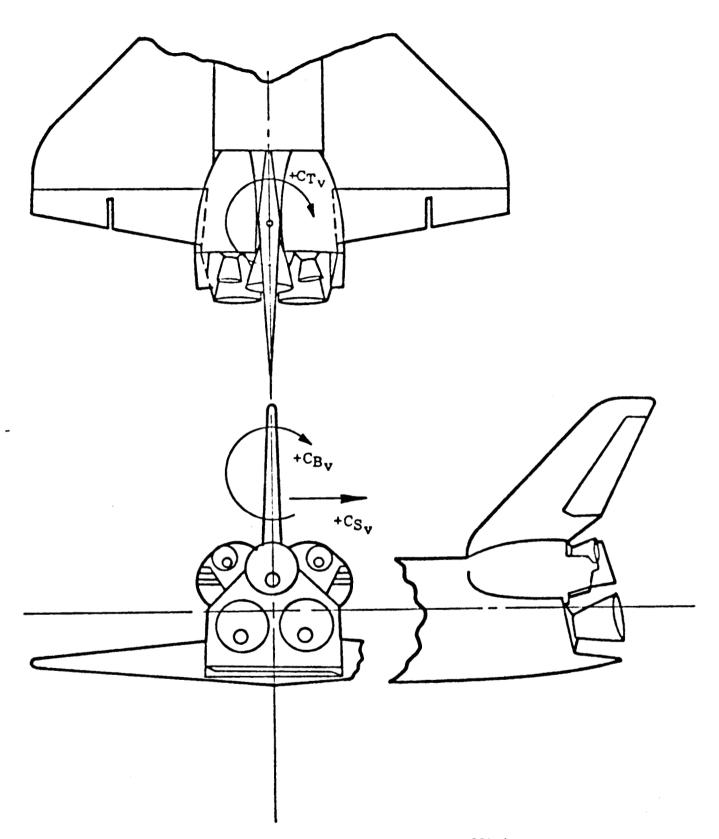


d. Wing Moment Reference Center Figure 1. Continued

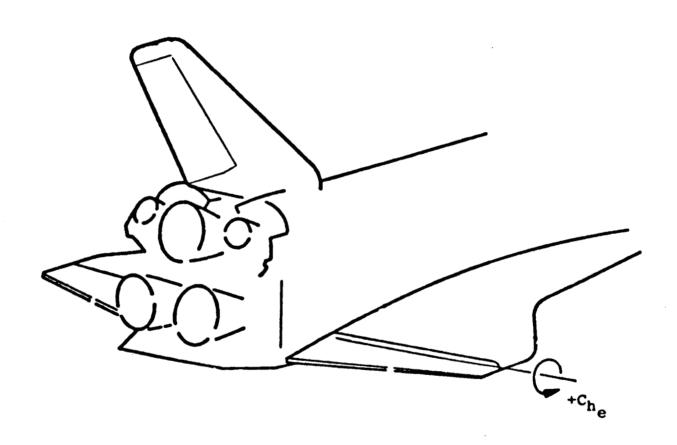


e. Vertical Stabilizer Balance Transfer Diagram Figure 1. Continued.

57

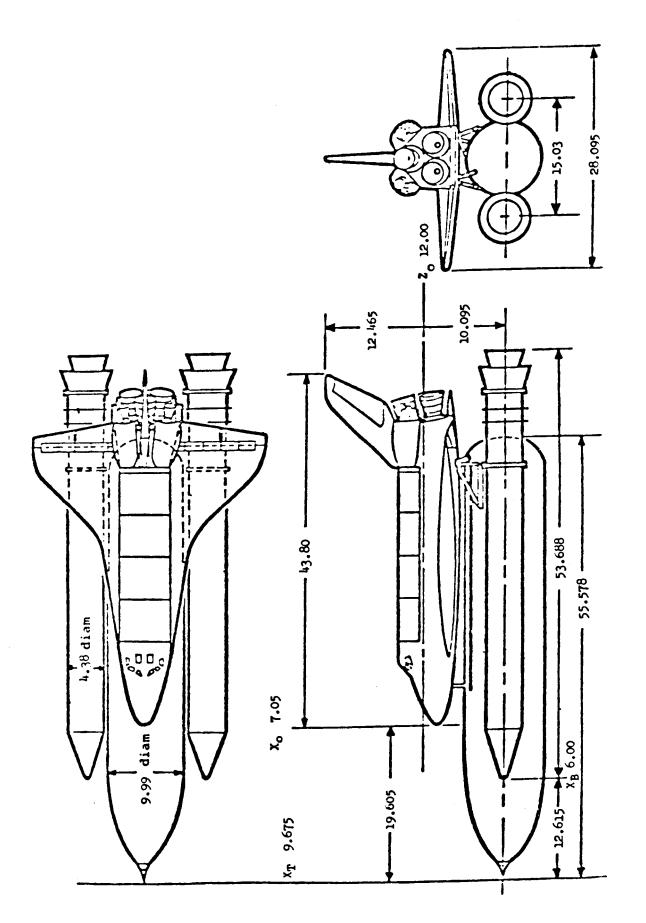


f. Definition of Vertical Stabilizer Coefficients Figure 1. Continued.

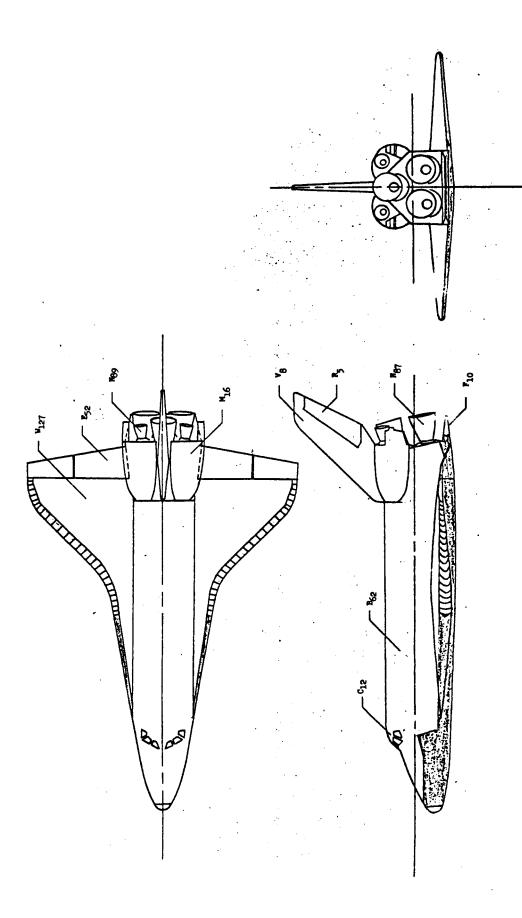


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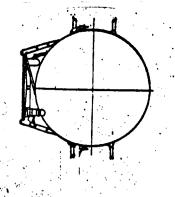
g. Definition of Elevon Hinge Moment Coefficients Figure 1. Concluded.

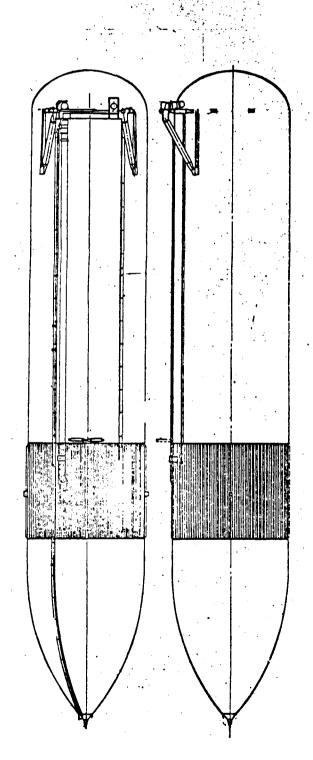


a. Major Model Component Dimensions Figure 2. Model sketches.

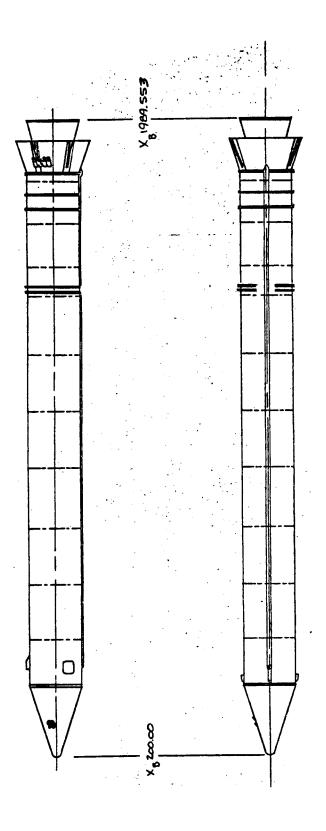


b. 102 Orbiter Figure 2. Continued.



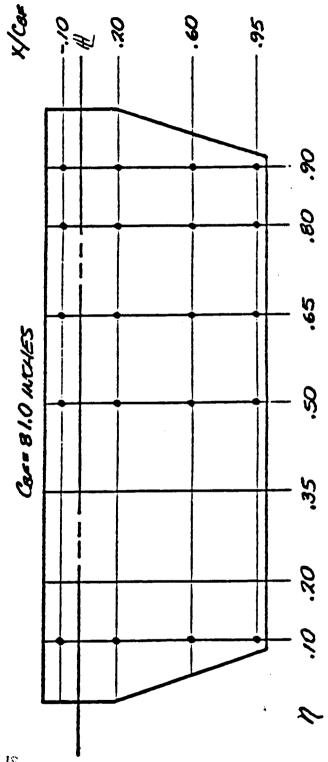


c. External Tank (T39) Figure 2. Continued.



d. Solid Rocket Booster (S27)Figure 2. Continued.

	りょ.	.10 401 402 403 404 405 406 401 40 B			4/4	424	432	440
(100)	۰,60	401			214	423	431	439
× / Co+ (80+) × / Co+ (404)	34. 03. 05. 01. 20. 03. 02. 01.	406			414	422	88	458
7.4	01	405			413	421	428	437
(to	80.	404			412	420	428	436
8) •	3	403			114	413	427	400
د / ده	02.	402			410	418	426	434
7	01:	401			50 409 410 411 412 413 414 415 416	.65 A1 418 419 420 421 422 423 424	80 425 424 427 428 429 430 431 432	.90 433 434 405 436 437 438 439 44D
1	•	0,	.20	.35	.50	.65	8	90:



e. Orbiter Body Flap Pressure Instrumentation Figure 2. Continued.

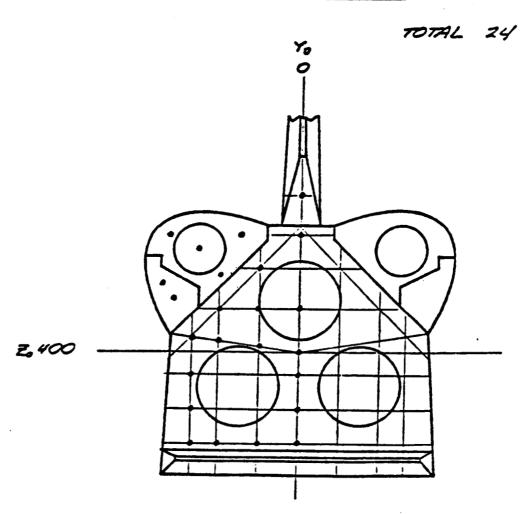
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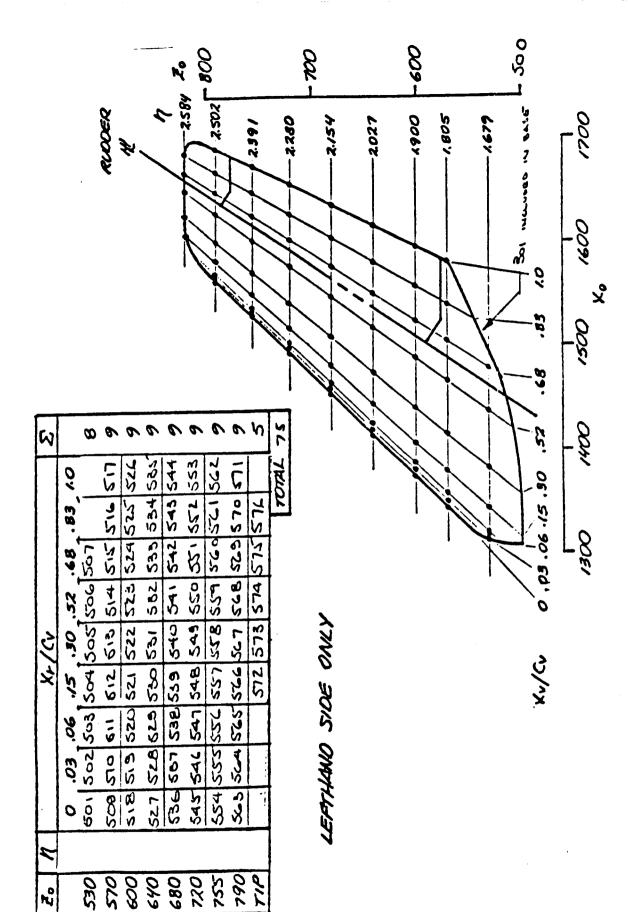
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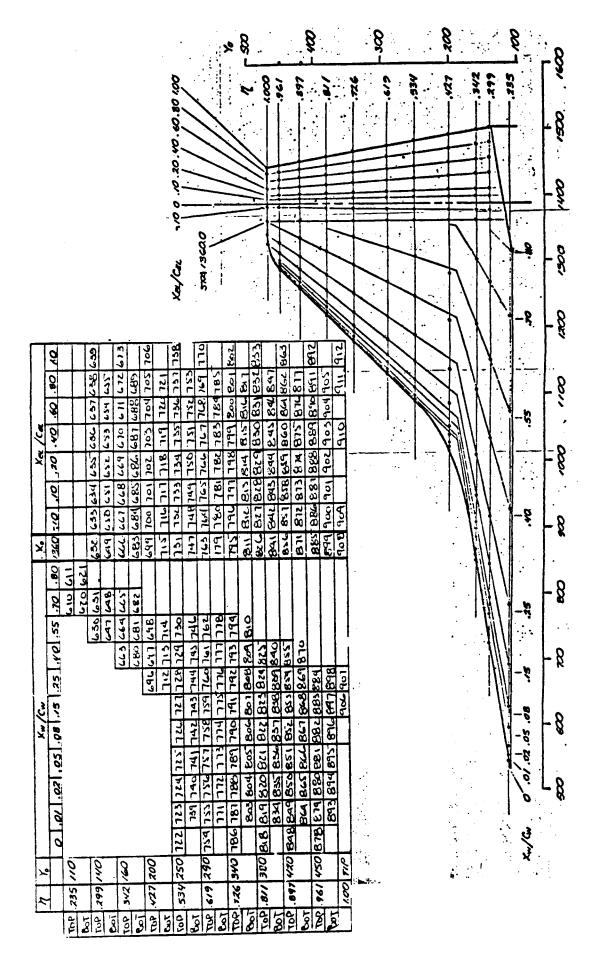
TAN	Z.	Yo	IAU	Z.	Yo	TAP E	Z.	Y.
301	532	0	311	302	-38	321	522	-103
	505				-78	u		
303	443	0	313	410	-78	323	439	-107
304	400	0	314	302	-78·	324	465	-130
305	376	0	315	414	-103			
306	340	0	316	376	-103			
307	302	0	317	340	-103			
302	478	-38	318	302	-103			
309	439	-38	319	514	-55			
310	405	-38	320	492	-68			



f. Orbiter Base Pressure Instrumentation Figure 2. Continued.

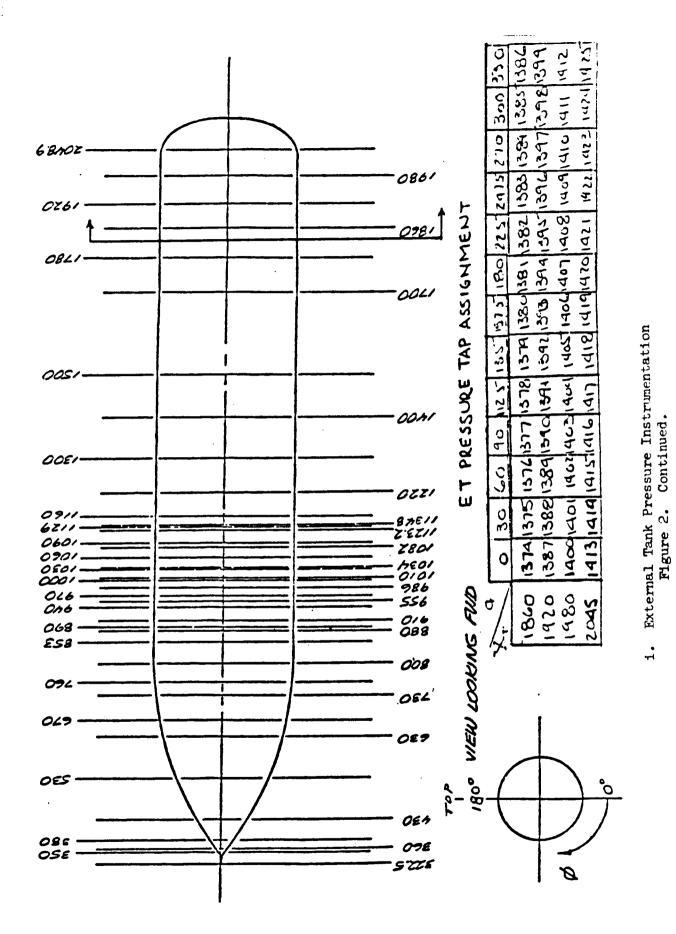


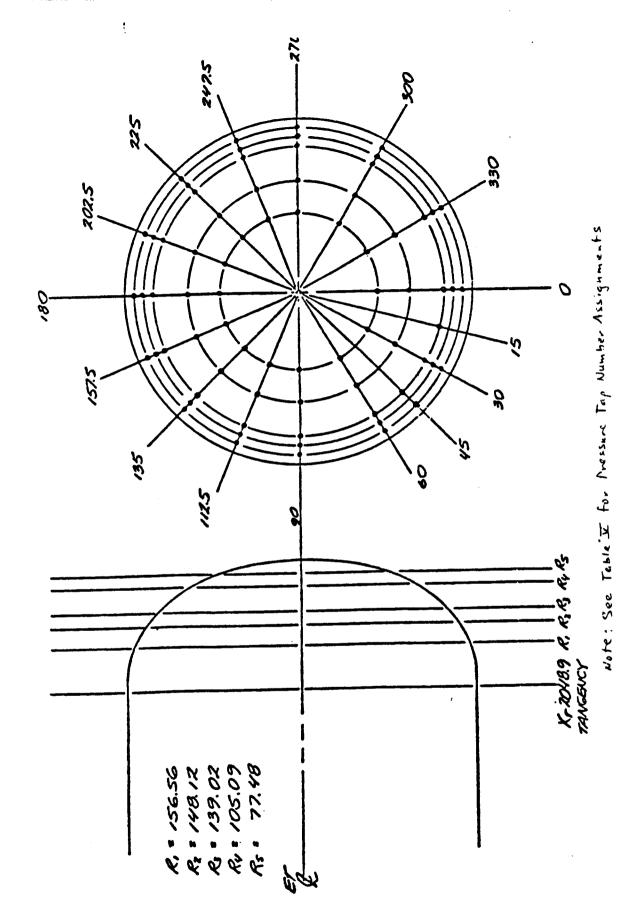
g. Orbiter Vertical Tail Pressure InstrumentationFigure 2. Continued.



(

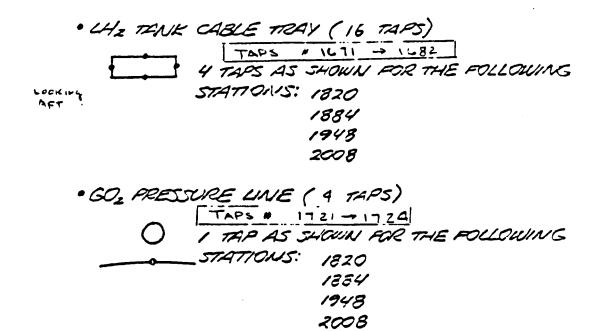
h. Orbiter Wing Pressure Instrumentation Figure 2. Continued.

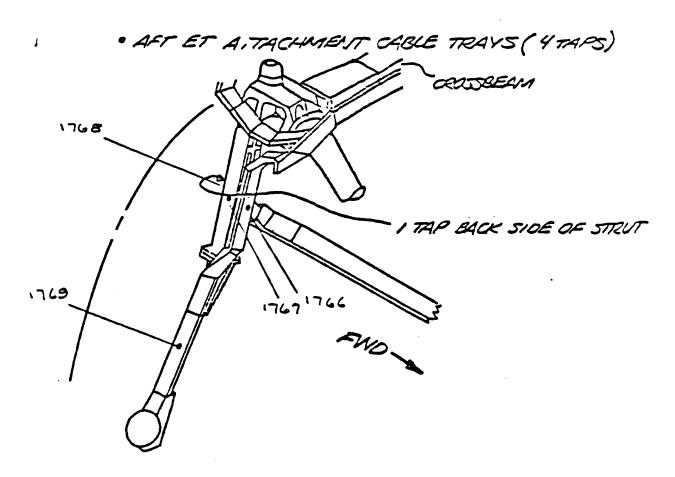




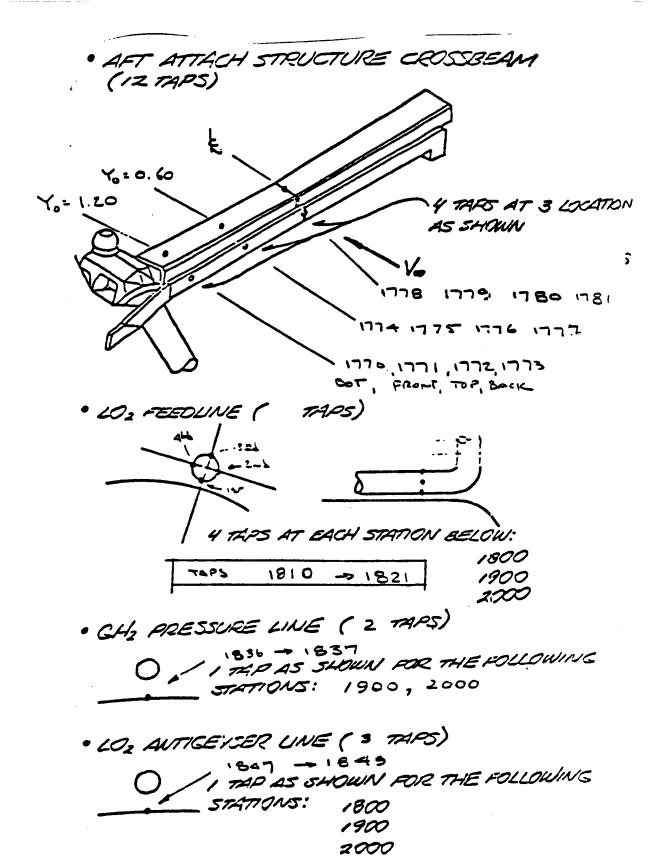
i. External Tank Base Pressure Instrumentation Figure 2.

Continued.



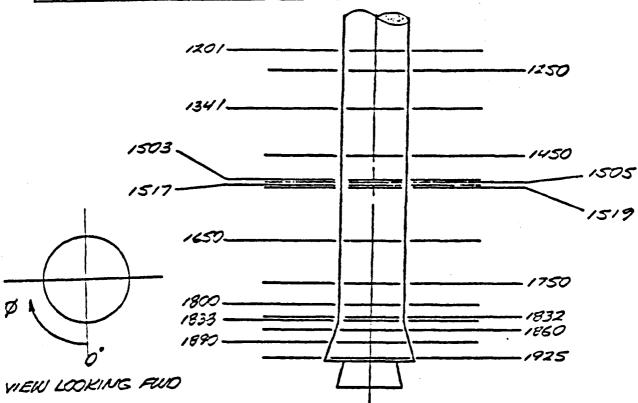


k. External Tank Protuberance Pressure Instrumentation Figure 2. Continued.



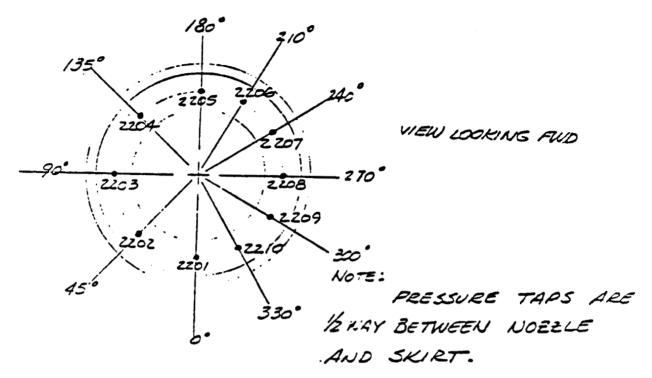
1. External Tank Protuberance Pressure Instrumentation Figure 2. Continued.

STA	0	45	26	90	94	135	180	225	247.5	270	292.5	3/5
1341	_		2078	. —	2079	-		-	_	_	1	
1450	2080	2081		_	_	208Z	2083	2084		2085		2086
1503	2087	Z058	وعمت	· —	2090	2091	2092	2093	_	2091		2095
1505	2096	2097		_		2098	2099		_	2101		
1517	2103	2.04	_	_	-	2/05	2106		_	2/08		
1519			•	_	2110	-	_	1	J	_	_	_
1650	2111	2112	2/13	_	2/14	2115	2116	2117	-	2/18		2119
1750	2/20	2/2/	_	_	_	2122	2/23	2/24		2125		2126
1800	2/27	2/28	2,29	_	2130	2131	2/32	2/33	-	2/34		2135
1832	2/36	2/37	_	_	1	2138	Z/39	2140		2/4/		2142
1838	2/43	2/44	_	-	-	2/45	2,46	2147		2146		2147
1860	2/50	2151	_	25						Z/57		
1890	2160	2161	_	2/62						2167		
1925	2170	2/7/		2.72		2/73	2174	2/75	2/76	2/77	Z/28,	2/79

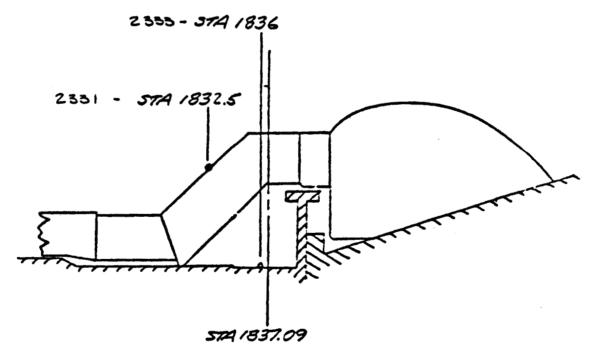


m. Solid Rocket Booster Pressure Instrumentation Figure 2. Continued.

· BASE PRESSURE INSTRUMENTATION



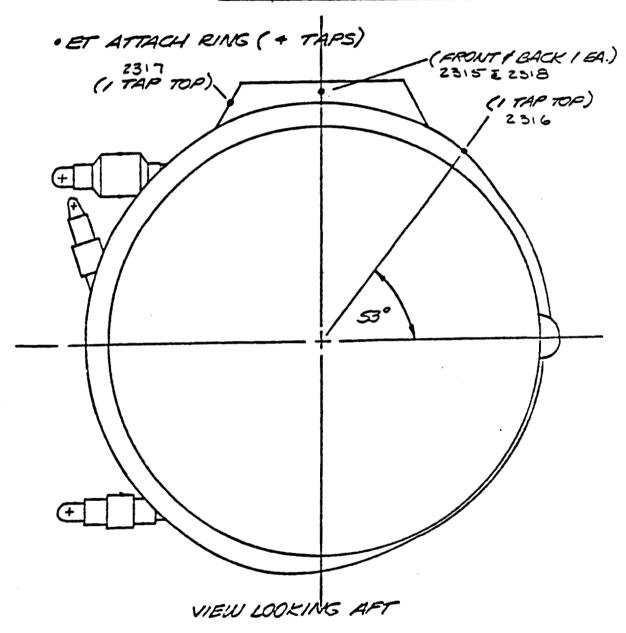
· AFT FAIRING-SYSTEMS TUNNEL (2 TAPS)



n. Solid Rocket Booster Base and Protuberance Pressure Instrumentation Figure 2. Continued.

- · CENTER SECTION-SYSTEMS TUNNEL (13 TAPS)
 - I TAP LOCATED TOP CENTERLINE OF FAIRING AT THE FOLLOWING SRB STATIONS:

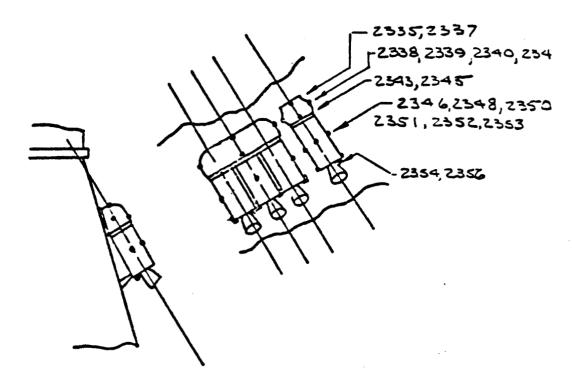
	T40 40	Y.	T)_2 40	٧ø	70 W	X3
i	2312	1201	2327	1531	2330	√ 80 0
	2313	1341	2328	1650		
-	2314	1503	2329	1726		



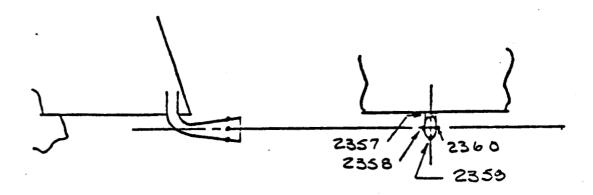
o. Solid Rocket Booster Protuberance Instrumentation Figure 2. Continued.

C. ROLL COLLEGE

· SEPARATION MOTOR FAIRINGS (16. TAPS)



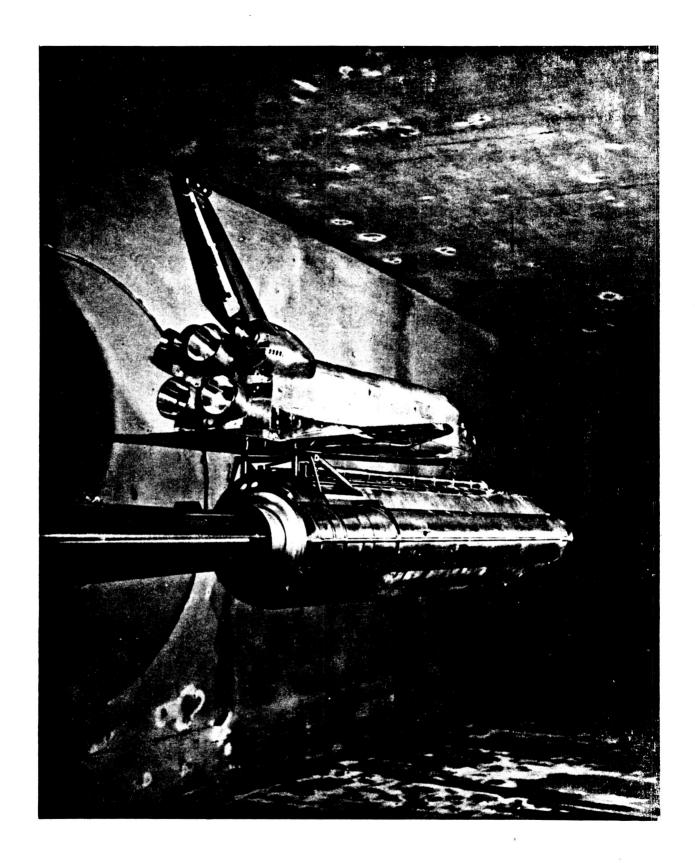
*TURBINE EXHAUST (4 TAPS). - TAPS ON ONE



p. Solid Rocket Booster Protuberance Instrumentation Figure 2. Concluded.



 a. Three-Quarter Front View of Model 470TS in the ARC 9x7 Foot UPWT
 Figure 3. Model Installation Photographs



b. Three-Quarter Rear View of Model 47 \emptyset TS in the ARC 9x7 Foot UPWT Figure 3. Concluded

APPENDIX

TABULATED SOURCE DATA